

**JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY
HYDERABAD.
B.TECH. MECHANICAL ENGINEERING**

IV Year		Semester I		
COURSE STRUCTURE				
CODE	SUBJECT	T	P/D	C
	Operations Research	4+1*	0	4
	Data Base Management Systems	4+1*	0	4
	Finite Element Methods	4+1*	0	4
	Instrumentation and Control Systems	4+1*	0	4
	ELECTIVE – I	4+1*	0	4
	Robotics			
	Computational Fluid Dynamics			
	Mechatronics			
	Advanced Data Structures and Algorithms			
	ELECTIVE – II	4+1*	0	4
	Unconventional Machining Processes			
	Nonconventional Sources of Energy			
	Power Plant Engineering			
	Unix and Shell programming			
	Heat Transfer Lab	0	3	2
	Production Drawing Practice and Instrumentation Lab	0	3	2
	TOTAL	30	6	28

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OPERATIONS RESEARCH

UNIT – I

Development – Definition– Characteristics and Phases – Types of models – operation Research models – applications.

ALLOCATION : Linear Programming Problem Formulation – Graphical solution – Simplex method – Artificial variables techniques -Two–phase method, Big-M method – Duality Principle.

UNIT – II

TRANSPORTATION PROBLEM – Formulation – Optimal solution, unbalanced transportation problem – Degeneracy. Assignment problem – Formulation – Optimal solution - Variants of Assignment Problem- Traveling Salesman problem.

SEQUENCING – Introduction – Flow –Shop sequencing – n jobs through two machines – n jobs through three machines – Job shop sequencing – two jobs through 'm' machines.

UNIT – III

REPLACEMENT : Introduction – Replacement of items that deteriorate with time – when money value is not counted and counted – Replacement of items that fail completely, group replacement.

UNIT – IV

THEORY OF GAMES : Introduction – Minimax (maximin) – Criterion and optimal strategy – Solution of games with saddle points – Rectangular games without saddle points – 2 X 2 games – dominance principle – m X 2 & 2 X n games -graphical method.

UNIT – V

WAITING LINES : Introduction – Single Channel – Poisson arrivals – exponential service times – with infinite population and finite population models– Multichannel – Poisson arrivals – exponential service times with infinite population single channel Poisson arrivals.

UNIT – VI

INVENTORY : Introduction – Single item – Deterministic models – Purchase inventory models with one price break and multiple price breaks – shortages are not allowed – Stochastic models – demand may be discrete variable or continuous variable – Instantaneous production. Instantaneous demand and continuous demand and no set up cost.

UNIT – VII

DYNAMIC PROGRAMMING : Introduction – Bellman's Principle of optimality – Applications of dynamic programming- capital budgeting problem – shortest path problem – linear programming problem.

UNIT – VIII

SIMULATION : Definition – Types of simulation models – phases of simulation– applications of simulation – Inventory and Queuing problems – Advantages and Disadvantages – Simulation Languages.

TEXT BOOK :

1. Operations Research / S.D.Sharma-Kedarnath
2. Introduction to O.R/Hiller & Libermann (TMH).

REFERENCES :

1. Operations Research /A.M.Natarajan,P.Balasubramani,A. Tamilarasi/Pearson Education.
2. Operations Research: Methods & Problems / Maurice Saseini, Arhur Yaspan & Lawrence Friedman
3. Operations Research / R.Pannerselvam,PHI Publications.
4. Operations Research / Wagner/ PHI Publications.
5. Operation Research /J.K.Sharma/MacMilan.
6. O.R/Wayne L.Winston/Thomson Brooks/cole
7. Introduction to O.R /Taha/PHI

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DATABASE MANAGEMENT SYSTEMS

UNIT – I

Data base System Applications, data base System VS file System – View of Data – Data Abstraction – Instances and Schemas – data Models – the ER Model – Relational Model – Other Models – Database Languages – DDL – DML – database Access for applications Programs – data base Users and Administrator – Transaction Management – data base System Structure – Storage Manager – the Query Processor

UNIT – II

History of Data base Systems. Data base design and ER diagrams – Beyond ER Design Entities, Attributes and Entity sets – Relationships and Relationship sets – Additional features of ER Model – Concept Design with the ER Model – Conceptual Design for Large enterprises.

UNIT – III

Introduction to the Relational Model – Integrity Constraint Over relations – Enforcing Integrity constraints – Querying relational data – Logical data base Design – Introduction to Views – Destroying /altering Tables and Views.

Relational Algebra – Selection and projection set operations – renaming – Joins – Division – Examples of Algebra overviews – Relational calculus – Tuple relational Calculus – Domain relational calculus – Expressive Power of Algebra and calculus.

UNIT – IV

Form of Basic SQL Query – Examples of Basic SQL Queries – Introduction to Nested Queries – Correlated Nested Queries Set – Comparison Operators – Aggregative Operators – NULL values – Comparison using Null values – Logical connectivity's – AND, OR and NOT – Impact on SQL Constructs – Outer Joins – Disallowing NULL values – Complex Integrity Constraints in SQL Triggers and Active Data bases.

UNIT – V

Schema refinement – Problems Caused by redundancy – Decompositions – Problem related to decomposition – reasoning about FDS – FIRST, SECOND, THIRD Normal forms – BCNF – Lossless join Decomposition – Dependency preserving Decomposition – Schema refinement in Data base Design – Multi valued Dependencies – FORTH Normal Form.

UNIT – VI

Transaction Concept- Transaction State- Implementation of Atomicity and Durability – Concurrent – Executions – Serializability- Recoverability – Implementation of Isolation – Testing for serializability- Lock – Based Protocols – Timestamp Based Protocols- Validation- Based Protocols – Multiple Granularity.

UNIT – VII

Recovery and Atomicity – Log – Based Recovery – Recovery with Concurrent Transactions – Buffer Management – Failure with loss of nonvolatile storage-Advance Recovery systems- Remote Backup systems.

UNIT – VIII

Data on External Storage – File Organization and Indexing – Cluster Indexes, Primary and Secondary Indexes – Index data Structures – Hash Based Indexing – Tree base Indexing – Comparison of File Organizations – Indexes and Performance Tuning- Intuitions for tree Indexes – Indexed Sequential Access Methods (ISAM) – B+ Trees: A Dynamic Index Structure.

TEXT BOOKS :

1. Data base Management Systems, Raghurama Krishnan, Johannes Gehrke, TATA McGrawHill 3rd Edition
2. Data base System Concepts, Silberschatz, Korth, McGraw hill, V edition.

REFERENCES :

1. Data base Systems design, Implementation, and Management, Peter Rob & Carlos Coronel 7th Edition.
2. Fundamentals of Database Systems, Elmasri Navrate Pearson Education
3. Introduction to Database Systems, C.J.Date Pearson Education

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FINITE ELEMENT METHODS

UNIT – I

Introduction to Finite Element Method for solving field problems. Stress and Equilibrium. Strain – Displacement relations. Stress – strain relations.

UNIT – II

One Dimensional problems : Finite element modeling coordinates and shape functions. Potential Energy approach : Assembly of Global stiffness matrix and load vector. Finite element equations, Treatment of boundary conditions, Quadratic shape functions.

UNIT – III

Analysis of Beams : Element stiffness matrix for two node, two degrees of freedom per node beam element.

UNIT – IV

Finite element modelling of two dimensional stress analysis with constant strain triangles and treatment of boundary conditions.

UNIT – V

Finite element modelling of Axisymmetric solids subjected to Axisymmetric loading with triangular elements.

UNIT-VI

Two dimensional four noded isoparametric elements and numerical integration.

UNIT – VII

Steady state heat transfer analysis : one dimensional analysis of a fin and two dimensional analysis of thin plate. Analysis of a uniform shaft subjected to torsion.

UNIT-VIII

Dynamic Analysis : Formulation of finite element model, element matrices, evaluation of Eigen values and Eigen vectors for a stepped bar and a beam.

TEXT BOOK :

1. Introduction to Finite Elements in Engineering / Chandruputla, Ashok and Belegundu / Prentice – Hall.
2. The Finite Element Methods in Engineering / SS Rao / Pergamon.

REFERENCES :

1. An introduction to Finite Element Method / JN Reddy / Me Graw Hill
2. Finite Element Methods/ Alavala/TMH
3. The Finite Element Method for Engineers – Kenneth H. Huebner, Donald L. Dewhirst, Douglas E. Smith and Ted G. Byrom / John Wiley & sons (ASIA) Pte Ltd.
4. Finite Element Analysis/ C.S.Krishna Murthy

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INSTRUMENTATION AND CONTROL SYSTEMS

UNIT – I

Definition – Basic principles of measurement – Measurement systems, generalized configuration and functional descriptions of measuring instruments – examples. Dynamic performance characteristics – sources of error, Classification and elimination of error.

UNIT – II

Measurement of Displacement: Theory and construction of various transducers to measure displacement – Piezo electric, Inductive, capacitance, resistance, ionization and Photo electric transducers, Calibration procedures.

MEASUREMENT OF TEMPERATURE : Classification – Ranges – Various Principles of measurement – Expansion, Electrical Resistance – Thermistor – Thermocouple – Pyrometers – Temperature Indicators..

UNIT – III

MEASUREMENT OF PRESSURE : Units – classification – different principles used. Manometers, Piston, Bourdon pressure gauges, Bellows – Diaphragm gauges. Low pressure measurement – Thermal conductivity gauges – ionization pressure gauges, Mcleod pressure gauge.

UNIT – IV

MEASUREMENT OF LEVEL : Direct method – Indirect methods – capacitive, ultrasonic, magnetic, cryogenic fuel level indicators – Bubbler level indicators.

FLOW MEASUREMENT : Rotameter, magnetic, Ultrasonic, Turbine flow meter, Hot – wire anemometer, Laser Doppler Anemometer (LDA).

UNIT – V

MEASUREMENT OF SPEED : Mechanical Tachometers – Electrical tachometers – Stroboscope, Noncontact type of tachometer

Measurement of Acceleration and Vibration : Different simple instruments – Principles of Seismic instruments – Vibrometer and accelerometer using this principle.

UNIT – VI

STRESS STRAIN MEASUREMENTS : Various types of stress and strain measurements – electrical strain gauge – gauge factor – method of usage of resistance strain gauge for bending compressive and tensile strains – usage for measuring torque, Strain gauge Rosettes.

UNIT – VII

MEASUREMENT OF HUMIDITY – Moisture content of gases, sling psychrometer, Absorption psychrometer, Dew point meter.

MEASUREMENT OF FORCE, TORQUE AND POWER- Elastic force meters, load cells, Torsion meters, Dynamometers.

UNIT – VIII

ELEMENTS OF CONTROL SYSTEMS : Introduction, Importance – Classification – Open and closed systems Servomechanisms–Examples with block diagrams–Temperature, speed & position control systems.

TEXT BOOKS :

1. Measurement Systems: Applications & design by D.S Kumar.
2. Mechanical Measurements / BeckWith, Marangoni, Linehard, PHI / PE

REFERENCES :

1. Measurement systems: Application and design, Doebelin Earnest. O. Adaptation by Manik and Dhanesh/ TMH
2. Instrumentation and Control systems/ S.Bhaskar/ Anuradha Agencies.
3. Experimental Methods for Engineers / Holman.
4. Mechanical and Industrial Measurements / R.K. Jain/ Khanna Publishers.
5. Instrumentation & mech. Measurements by A.K. Tayal ,Galgotia Publications
6. Instrumentation, measurement & analysis by B.C.Nakra & K.K.Choudhary, TMH
7. Mechanical Measurements /sahani

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ROBOTICS
(ELECTIVE – I)

UNIT – I

Introduction: Automation and Robotics, CAD/CAM and Robotics – An over view of Robotics – present and future applications – classification by coordinate system and control system.

UNIT – II

Components of the Industrial Robotics: Function line diagram representation of robot arms, common types of arms. Components, Architecture, number of degrees of freedom – Requirements and challenges of end effectors, determination of the end effectors, comparison of Electric, Hydraulic and Pneumatic types of locomotion devices.

UNIT – III

Motion Analysis: Homogeneous transformations as applicable to rotation and translation – problems.

UNIT – IV

Manipulator Kinematics: Specifications of matrices, D-H notation joint coordinates and world coordinates Forward and inverse kinematics – problems.

UNIT – V

Differential transformation and manipulators, Jacobians – problems. Dynamics: Lagrange – Euler and Newton – Euler formations – Problems.

UNIT VI

Trajectory planning and avoidance of obstacles, path planning, Skew motion, joint integrated motion – straight line motion – Robot programming, languages and software packages.

UNIT VII

Robot actuators and Feed back components: Actuators: Pneumatic, Hydraulic actuators, electric & stepper motors. Feedback components: position sensors – potentiometers, resolvers, encoders – Velocity sensors.

UNIT VIII

Robot Application in Manufacturing: Material Transfer - Material handling, loading and unloading- Processing - spot and continuous arc welding & spray painting - Assembly and Inspection.

TEXT BOOKS :

1. Industrial Robotics / Groover M P / Pearson Edu.
2. Robotics and Control / Mittal R K & Nagrath I J / TMH.

REFERENCES :

1. Robotics / Fu K S/ McGraw Hill.
2. An Introduction to Robot Technology, / P. Coiffet and M. Chaironze / Kogam Page Ltd. 1983 London.
3. Robotic Engineering / Richard D. Klaffer, Prentice Hall
4. Robot Analysis and Intelligence / Asada and Slow time / Wiley Inter-Science.
5. Introduction to Robotics / John J Craig / Pearson Edu.
6. Robot Dynamics & Control – Mark W. Spong and M. Vidyasagar / John Wiley & Sons (ASIA) Pte Ltd.

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COMPUTATIONAL FLUID DYNAMICS
(ELECTIVE – I)

UNIT-I

Elementary details in numerical Techniques: Number system and errors, Representation of integers, Fractions, Floating point Arithmetic, loss of significance and error propagation, condition and instability, computational methods for error estimation, Convergence of Sequences.

UNIT – II

Applied Numerical Methods: Solution of a system of simultaneous Linear Algebraic Equations, iterative schemes of Matrix Inversion, Direct Methods for Matrix inversion, Direct Methods for banded matrices.

UNIT - III

Finite Difference Applications in Heat conduction and Convection – Heat conduction, steady heat conduction in a rectangular geometry, transient heat conduction, finite difference application in convective heat transfer, closure.

UNIT - IV

Finite Differences, discretization, consistency, stability, and Fundamentals of fluid flow modeling: Introduction, elementary finite difference quotients, implementation aspects of finite-difference equations, consistency, explicit and implicit methods.

UNIT - V

Introduction to first order wave equation, stability of hyperbolic and elliptic equations, fundamentals of fluid flow modeling, conservative property, the upwind scheme.

UNIT - VI

Review of Equations Governing Fluid Flow and Heat Transfer: Introduction, conservation of mass, Newton's second law of motion, expanded forms of Navier-stokes equations, conservation of energy principle, special forms of the Navier-stokes equations.

UNIT - VII

Steady flow, dimensionless form of Momentum and Energy equations, Stokes equation, conservative body force fields, stream function - Vorticity formulation.

UNIT -VIII

Finite Volume Method: Approximation of surface integrals, volume integrals, interpolation and differentiation practices, Upwind interpolation, Linear interpolation and Quadratic interpolation.

TEXT BOOK :

1. Numerical heat transfer and fluid flow / Suhas V. Patankar- Butter-worth Publishers
2. Computational fluid dynamics - Basics with applications - John. D. Anderson / Mc Graw Hill.

REFERENCES :

1. Computational Fluid Flow and Heat Transfer/ Niyogi, Pearson Publications
2. Fundamentals of Computational Fluid Dynamics – Tapan K. Sengupta / Universities Press.

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MECHATRONICS
(ELECTIVE – I)

UNIT – I

INTRODUCTION : Definition – Trends - Control Methods: Standalone , PC Based (Real Time Operating Systems, Graphical User Interface , Simulation) - Applications: SPM, Robot, CNC, FMS, CIM.

UNIT – II

SIGNAL CONDITIONING : Introduction – Hardware - Digital I/O , Analog input – ADC , resolution , speed channels

Filtering Noise using passive components – Resistors, capacitors - Amplifying signals using OP amps – Software - Digital Signal Processing – Low pass , high pass , notch filtering

UNIT – III

PRECISION MECHANICAL SYSTEMS : Pneumatic Actuation Systems - Electro-pneumatic Actuation Systems - Hydraulic Actuation Systems - Electro-hydraulic Actuation Systems - Timing Belts - Ball Screw and Nut - Linear Motion Guides - Linear Bearings - Harmonic Transmission - Bearings- Motor / Drive Selection.

UNIT – IV

ELECTRONIC INTERFACE SUBSYSTEMS : TTL, CMOS interfacing - Sensor interfacing - Actuator interfacing – solenoids , motors Isolation schemes- opto coupling, buffer IC's - Protection schemes – circuit breakers , over current sensing , resettable fuses , thermal dissipation - Power Supply - Bipolar transistors / mosfets

UNIT – V

ELECTROMECHANICAL DRIVES : Relays and Solenoids - Stepper Motors - DC brushed motors - DC brushless motors - DC servo motors - 4-quadrant servo drives , PWM's - Pulse Width Modulation - Variable Frequency Drives, Vector Drives - Drive System load calculation.

UNIT – VI

MICROCONTROLLERS OVERVIEW : 8051 Microcontroller , micro processor structure - Digital Interfacing - Analog Interfacing - Digital to Analog Convertors - Analog to Digital Convertors - Applications. Programming –Assembly , C (LED Blinking , Voltage measurement using ADC).

UNIT – VII

PROGRAMMABLE LOGIC CONTROLLERS : Basic Structure - Programming : Ladder diagram - Timers, Internal Relays and Counters - Shift Registers - Master and Jump Controls - Data Handling - Analog input / output - PLC Selection - Application.

Unit – VIII

PROGRAMMABLE MOTION CONTROLLERS : Introduction - System Transfer Function - Laplace transform and its application in analysing differential equation of a control system - Feedback Devices : Position , Velocity Sensors - Optical Incremental encoders - Proximity Sensors : Inductive , Capacitive , Infrared - Continuous and discrete processes - Control System Performance & tuning - Digital Controllers - P , PI , PID Control - Control modes – Position , Velocity and Torque - Velocity Profiles – Trapezoidal - S. Curve - Electronic Gearing - Controlled Velocity Profile - Multi axis Interpolation , PTP , Linear , Circular - Core functionalities – Home , Record position , Go to Position - Applications : SPM, Robotics.

TEXT BOOKS :

1. Mechatronics Electronics Control Systems in Mechanical and Electrical Engineering by W Bolton, Pearson Education Press, 3rd edition, 2005.
2. Mechatronics/M.D.Singh/J.G.Joshi/PHI.

REFERENCES :

1. Mechatronics Source Book by Newton C Braga, Thomson Publications, Chennai.
2. Mechatronics – N. Shanmugam / Anuradha Agencies Publisers.
3. Mechatronics System Design / Devdas shetty/Richard/Thomson.

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ADVANCED DATA STRUCTURES AND ALGORITHMS
(ELECTIVE – I)

Unit I:-

C++ Class Overview- Class Definition, Objects, Class Members, Access Control, Class Scope, Constructors and destructors, parameter passing methods, Inline functions, static class members, this pointer, friend functions, dynamic memory allocation and deallocation (new and delete), exception handling.

Unit II:-

Function Overloading, Operator Overloading, Generic Programming- Function and class templates, Inheritance basics, base and derived classes, inheritance types, base class access control, runtime polymorphism using virtual functions, abstract classes, streams I/O.

Unit III:-

Algorithms, performance analysis-time complexity and space complexity, O-notation, Omega notation and Theta notation, Review of basic data structures - the list ADT, stack ADT, queue ADT, implementation using template classes in C++, sparse matrix representation.

Unit IV:-

Dictionaries, linear list representation, skip list representation, operations- insertion, deletion and searching, hash table representation, hash functions, collision resolution-separate chaining, open addressing-linear probing, quadratic probing, double hashing, rehashing, extendible hashing, comparison of hashing and skip lists.

Unit V:-

Priority Queues – Definition, ADT, Realizing a Priority Queue using Heaps, Definition, insertion, Deletion, Application-Heap Sort, External Sorting- Model for external sorting, Multiway merge, Polyphase merge.

Unit VI:-

Search trees (part I) : Binary search trees, definition, ADT, implementation, operations-searching, insertion and deletion, Balanced search trees- AVL trees, definition, height of an AVL tree, representation, operations-insertion, deletion and searching.

Search trees (part II) : Introduction to Red –Black trees and Splay Trees, B-Trees-B-Tree of order m, height of a B-Tree, insertion, deletion and searching, Comparison of Search Trees.

Unit VII:-

Divide and Conquer- General method, applications – Binary search, merge sort, quick sort, Strassen's matrix multiplication

Efficient non recursive tree traversal algorithms, Biconnected components. Disjoint set operations, union and find algorithms.

Unit VIII:-

Greedy method and Dynamic programming : General method (Greedy), Minimum cost spanning trees, Job sequencing with deadlines, General method (Dynamic Programming), Optimal binary search trees, 0/1 knapsack problem, Ordering Matrix Multiplications

TEXT BOOKS :

1. Data Structures and Algorithm Analysis in C++, Mark Allen Weiss, Pearson Education, second edition.
2. Data structures, Algorithms and Applications in C++, S.Sahni, University press (India) pvt ltd, 2nd edition, Orient Longman pvt.ltd.

REFERENCE :

1. Data structures and Algorithms in C++, Michael T.Goodrich, R.Tamassia and D.Mount, Seventh Edition Wiley student edition, John Wiley and Sons.
2. Data Structures and Algorithms in C++, Third Edition, Adam Drozdek, Thomson
3. Problem solving with C++, The OOP, Fourth edition, W.Savitch, Pearson education.
4. C++, The Complete Reference, 4th Edition, Herbert Schildt, TMH.
5. Data structures using C and C++, Langsam, Augenstein and Tanenbaum, PHI/Pearson

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UNCONVENTIONAL MACHINING PROCESSES
(ELECTIVE – II)

UNIT – I

INTRODUCTION – Need for non-traditional machining methods-Classification of modern machining processes – considerations in process selection. Materials. Applications.

UNIT II

Ultrasonic machining – Elements of the process, mechanics of metal removal process parameters, economic considerations, applications and limitations, recent development.

UNIT – III

Abrasive jet machining, Water jet machining and abrasive water jet machine : Basic principles, equipments, process variables, mechanics of metal removal, MRR, application and limitations.

UNIT - IV

ELECTRO – CHEMICAL PROCESSES : Fundamentals of electro chemical machining, electrochemical grinding, electro chemical honing and deburring process, metal removal rate in ECM, Tool design, Surface finish and accuracy economic aspects of ECM – Simple problems for estimation of metal removal rate. Fundamentals of chemical, machining, advantages and applications.

UNIT - V

THERMAL METAL REMOVAL PROCESSES : General Principle and applications of Electric Discharge Machining, Electric Discharge Grinding and electric discharge wire cutting processes – Power circuits for EDM, Mechanics of metal removal in EDM, Process parameters, selection of tool electrode and dielectric fluids, methods surface finish and machining accuracy, characteristics of spark eroded surface and machine tool selection. Wire EDM, principle, applications.

UNIT – VI

Generation and control of electron beam for machining, theory of electron beam machining, comparison of thermal and non-thermal processes –General Principle and application of laser beam machining – thermal features, cutting speed and accuracy of cut.

UNIT-VII

Application of plasma for machining, metal removal mechanism, process parameters, accuracy and surface finish and other applications of plasma in manufacturing industries.
Chemical machining-principle- maskants –etchants- applications.

UNIT – VIII

Magnetic abrasive finishing, Abrasive flow finishing, Electrostream drilling, Shaped tube electrolytic machining.

TEXT BOOK :

1. Advanced machining processes/ VK Jain/ Allied publishers.

REFERENCES :

1. Modern Machining Process / Pandey P.C. and Shah H.S./ TMH.
2. New Technology / Bhattacharya A/ The Institution of Engineers, India 1984.
2. Modern Production / Operations Management / Baffa & Rakesh Sarin.

REFERENCES :

1. Operations Management – S.N. Chary.
2. Inventory Control Theory and Practice / Martin K. Starr and David W. Miller.
3. Reliability Engineering & Quality Engineering by Dr. C. Nadha Muni Reddy and Dr. K. Vijaya Kumar Reddy, Galgotia Publications, Pvt., Limited.
4. Production Control A Quantitative Approach / John E. Biegel.
5. Production Control / Moore.
6. Operations Management / Joseph Monks.

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NON-CONVENTIONAL SOURCES OF ENERGY
(ELECTIVE - II)

UNIT – I

PRINCIPLES OF SOLAR RADIATION : Role and potential of new and renewable source, the solar energy option, Environmental impact of solar power, physics of the sun, the solar constant, extraterrestrial and terrestrial solar radiation, solar radiation on tilted surface, instruments for measuring solar radiation and sun shine, solar radiation data.

UNIT-II

SOLAR ENERGY COLLECTION : Flat plate and concentrating collectors, classification of concentrating collectors, orientation and thermal analysis, advanced collectors.

UNIT-III

SOLAR ENERGY STORAGE AND APPLICATIONS : Different methods, Sensible, latent heat and stratified storage, solar ponds. Solar Applications- solar heating/cooling technique, solar distillation and drying, photovoltaic energy conversion.

UNIT-IV

WIND ENERGY : Sources and potentials, horizontal and vertical axis windmills, performance characteristics, Betz criteria

UNIT-V

BIO-MASS : Principles of Bio-Conversion, Anaerobic/aerobic digestion, types of Bio-gas digesters, gas yield, combustion characteristics of bio-gas, utilization for cooking, I.C.Engine operation and economic aspects.

UNIT-VI

GEO THERMAL ENERGY : Resources, types of wells, methods of harnessing the energy, potential in India.

UNIT-VII

OCEAN ENERGY : OTEC, Principles utilization, setting of OTEC plants, thermodynamic cycles. Tidal and wave energy: Potential and conversion techniques, mini-hydel power plants, and their economics.

UNIT-VIII

DIRECT ENERGY CONVERSION : Need for DEC, Carnot cycle, limitations, principles of DEC. Thermo-electric generators, seebeck, peltier and joul Thomson effects, Figure of merit, materials, applications, MHD generators, principles, dissociation and ionization, hall effect, magnetic flux, MHD accelerator, MHD Engine, power generation systems, electron gas dynamic conversion, economic aspects. Fuel cells, principles, faraday's law's, thermodynamic aspects, selection of fuels and operating conditions.

TEXT BOOKS:

1. Renewable energy resources/ Tiwari and Ghosal/ Narosa.
2. Non-Conventional Energy Sources /G.D. Rai

REFERENCES:

1. Renewable Energy Sources /Twidell & Weir
2. Solar Energy /Sukhame
3. Splar Power Engineering / B.S Magal Frank Kreith & J.F Kreith.
4. Principles of Solar Energy / Frank Krieth & John F Kreider.
5. Non-Conventional Energy / Ashok V Desai /Wiley Eastern.
6. Non-Conventional Energy Systems / K Mittal /Wheeler
7. Renewable Energy Technologies /Ramesh & Kumar /Narosa

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**POWER PLANT ENGINEERING
(ELECTIVE - II)**

UNIT – I

Introduction to the Sources of Energy – Resources and Development of Power in India.

STEAM POWER PLANT : Plant Layout, Working of different Circuits, Fuel and handling equipments, types of coals, coal handling, choice of handling equipment, coal storage, Ash handling systems.

UNIT II

STEAM POWER PLANT : COMBUSTION PROCESS : Properties of coal – overfeed and underfeed fuel beds, traveling grate stokers, spreader stokers, retort stokers, pulverized fuel burning system and its components, combustion needs and draught system, cyclone furnace, design and construction, Dust collectors, cooling towers and heat rejection. Corrosion and feed water treatment.

UNIT – III

INTERNAL COMBUSTION ENGINE PLANT : DIESEL POWER PLANT: Introduction – IC Engines, types, construction– Plant layout with auxiliaries – fuel supply system, air starting equipment, lubrication and cooling system – super charging.

UNIT IV

GAS TURBINE PLANT : Introduction – classification - construction – Layout with auxiliaries – Principles of working of closed and open cycle gas turbines. Combined Cycle Power Plants and comparison.

UNIT – V

HYDRO ELECTRIC POWER PLANT: Water power – Hydrological cycle / flow measurement – drainage area characteristics – Hydrographs – storage and Pondage – classification of dams and spill ways.
HYDRO PROJECTS AND PLANT: Classification – Typical layouts – plant auxiliaries – plant operation pumped storage plants.

UNIT VI

POWER FROM NON-CONVENTIONAL SOURCES: Utilization of Solar- Collectors- Principle of Working, Wind Energy – types – HAWT, VAWT -Tidal Energy.
DIRECT ENERGY CONVERSION: Solar energy, Fuel cells, Thermo electric and Thermo ionic, MHD generation.

UNIT – VII

NUCLEAR POWER STATION : Nuclear fuel – breeding and fertile materials – Nuclear reactor – reactor operation.
TYPES OF REACTORS: Pressurized water reactor, Boiling water reactor, sodium-graphite reactor, fast Breeder Reactor, Homogeneous Reactor, Gas cooled Reactor, Radiation hazards and shielding – radioactive waste disposal.

UNIT – VIII

POWER PLANT ECONOMICS AND ENVIRONMENTAL CONSIDERATIONS: Capital cost, investment of fixed charges, operating costs, general arrangement of power distribution, Load curves, load duration curve.
Definitions of connected load, Maximum demand, demand factor, average load, load factor, diversity factor – related exercises.
Effluents from power plants and Impact on environment – pollutants and pollution standards – Methods of Pollution control.

TEXT BOOK :

1. A Text Book of Power Plant Engineering / Rajput / Laxmi Publications
2. Power Plant Engineering – P.C.Sharma / S.K.Kataria Pub

REFERENCES :

1. Power Plant Engineering: P.K.Nag/ II Edition /TMH.
2. Power plant Engineering/ Ramalingam/ Scietech Publishers
3. A Course in Power Plant Engineering: / Arora and S. Domkundwar.
4. Power station Engineering – ElWakil / McHill.
5. An Introduction to Power Plant Technology / G.D. Rai.
6. Power plant Engg - Elanchezhian- I.K. International Pub.

2006-2007

JAWAHAR LAL NEHRU TECHNOLOGICAL UNIVERSITY
HYDERABAD

IV Year B.Tech. M.E. I-Sem

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UNIX AND SHELL PROGRAMMING
(ELECTIVE-II)

Unit I:

Introduction to Unix:- Architecture of Unix, Features of Unix , Unix Commands – PATH, man, echo, printf, script, passwd, uname, who, date, stty, pwd, cd, mkdir, rmdir, ls, cp, mv, rm, cat, more, wc, lp, od, tar, gzip.

Unit II :

Unix Utilities:- Introduction to unix file system, vi editor, file handling utilities, security by file permissions, process utilities, disk utilities, networking commands, unlink, du, df, mount, umount, find, unmask, ulimit, ps, w, finger, arp, ftp, telnet, rlogin. Text processing utilities and backup utilities , detailed commands to be covered are tail, head , sort, nl, uniq, grep, egrep, fgrep, cut, paste, join, tee, pg, comm, cmp, diff, tr, awk, cpio

Unit III :

Introduction to Shells :

Unix Session, Standard Streams, Redirection, Pipes, Tee Command, Command Execution, Command-Line Editing, Quotes, Command Substitution, Job Control, Aliases, Variables, Predefined Variables, Options, Shell/Environment Customization.

Filters :

Filters and Pipes, Concatenating files, Display Beginning and End of files, Cut and Paste, Sorting, Translating Characters, Files with Duplicate Lines, Count characters, Words or Lines, Comparing Files.

Unit IV :

Grep :

Operation, grep Family, Searching for File Content.

Sed :

Scripts, Operation, Addresses, commands, Applications, grep and sed.

Unit V :

awk:

Execution, Fields and Records, Scripts, Operations, Patterns, Actions, Associative Arrays, String Functions, String Functions, Mathematical Functions, User – Defined Functions, Using System commands in awk, Applications, awk and grep, sed and awk.

Unit VI :

Interactive Korn Shell :

Korn Shell Features, Two Special Files, Variables, Output, Input, Exit Status of a Command, eval Command, Environmental Variables, Options, Startup Scripts, Command History, Command Execution Process.

Korn Shell Programming :

Basic Script concepts, Expressions, Decisions: Making Selections, Repetition, special Parameters and Variables, changing Positional Parameters, Argument Validation, Debugging Scripts, Script Examples.

Unit VII :

Interactive C Shell :

C shell features, Two Special Files, Variables, Output, Input, Exit Status of a Command, eval Command, Environmental Variables, On-Off Variables, Startup and Shutdown Scripts, Command History, Command Execution Scripts.

C Shell Programming :

Basic Script concepts, Expressions, Decisions: Making Selections, Repetition, special Parameters and Variables, changing Positional Parameters, Argument Validation, Debugging Scripts, Script Examples.

Unit VIII :

File Management :

File Structures, System Calls for File Management – create, open, close, read, write, lseek, link, symlink, unlink, stat, fstat, lstat, chmod, chown, Directory API – opendir, readdir, closedir, mkdir, rmdir, umask.

TEXT BOOKS :

1. Unix and shell Programming Behrouz A. Forouzan, Richard F. Gilberg. Thomson

2. Your Unix the ultimate guide, Sumitabha Das, TMH. 2nd Edition.

REFERENCES :

1. Unix for programmers and users, 3rd edition, Graham Glass, King Ables, Pearson Education.
2. Unix programming environment, Kernighan and Pike, PHI. / Pearson Education
3. The Complete Reference Unix, Rosen, Host, Klee, Farber, Rosinski, Second Edition, T

2007-08

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IV Year B.Tech. M.E. I-Sem

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HEAT TRANSFER LAB

1. Composite Slab Apparatus – Overall heat transfer co-efficient.
2. Heat transfer through lagged pipe.
3. Heat Transfer through a Concentric Sphere
4. Thermal Conductivity of given metal rod.
5. Heat transfer in pin-fin
6. Experiment on Transient Heat Conduction
7. Heat transfer in forced convection apparatus.
8. Heat transfer in natural convection
9. Parallel and counter flow heat exchanger.
10. Emissivity apparatus.
11. Stefan Boltzman Apparatus.
12. Heat transfer in drop and film wise condensation.
13. Critical Heat flux apparatus.
14. Study of heat pipe and its demonstration.
15. Study of Two – Phase flow.

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PRODUCTION DRAWING PRACTICE AND INSTRUMENTATION LAB

UNIT – I

Conventional representation of Materials – conventional representation of parts – screw joints, welded joints, springs, gears, electrical, hydraulic and pneumatic circuits – methods of indicating notes on drawings.

UNIT – II

Limits and Fits : Types of fits, exercises involving selection / interpretation of fits and estimation of limits from tables.

UNIT – III

Form and Positional Tolerances : Introduction and indication of the tolerances of form and position on drawings, deformation of runout and total runout and their indication.

UNIT – IV

Surface roughness and its indication : Definitions – finishes obtainable from various manufacturing processes, recommended surface roughness on mechanical components.

UNIT – V

Heat treatment and surface treatment symbols used on drawings.

UNIT – VI

Detailed and Part drawings: Drawing of parts from assembly drawings with indications of size, tolerances, roughness, form and position errors etc.

UNIT – VII

Part drawing using computer aided drafting by CAD software

TEXT BOOKS :

1. Production and Drawing – K.L. Narayana & P. Kannaiah/ New Age
2. machine Drawing with Auto CAD- Pohit and Ghosh, PE

REFERENCE :

1. Geometric dimensioning and tolerancing- James D. Meadows/ B.S Publications
2. Engineering Metrology, R.K. Jain, Khanna Publications

(B) INSTRUMENTATION LAB

1. Calibration of Pressure Gauges
2. Calibration of transducer for temperature measurement.
3. Study and calibration of LVDT transducer for displacement measurement.
4. Calibration of strain gauge for temperature measurement.
5. Calibration of thermocouple for temperature measurement.
6. Calibration of capacitive transducer for angular displacement.
7. Study and calibration of photo and magnetic speed pickups for the measurement of speed.
8. Calibration of resistance temperature detector for temperature measurement.
9. Study and calibration of a rotometer for flow measurement.
10. Study and use of a Seismic pickup for the measurement of vibration amplitude of an engine bed at various loads.
11. Study and calibration of McLeod gauge for low pressure.