2007-2008

JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY
HYDERABAD

B.TECH. ELECTRONICS AND INSTRUMENTATION ENGINEERING

II YEAR I-SEMESTER
COURSE STRUCTURE

CODE	SUBJECT	T	P	C
	Mathematics – III	4+1*	-	4
	Electrical Technology	4+1 *	-	4
	Electromagnetic Waves and Transmission Lines	4+1 *	-	4
	Signals and Systems	4+1 *	-	4
	Pulse and Digital Circuits	4+1 *	-	4
	Switching Theory and Logic Design	4+1*	-	4
	Electrical Technology Lab	-	3	2
	Pulse and Digital Circuits Lab	-	3	2
	TOTAL	**30**	**6**	**28**

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II Year B.Tech. EIE I-Sem	**T**	**P**	**C**
	4+1*	**0**	**4**

MATHEMATICS – III

UNIT – I

Special functions: Gamma and Beta Functions – Their properties – evaluation of improper integrals. Bessel functions – properties – Recurrence relations – Orthogonality. Legendre polynomials – Properties – Rodrigue's formula – Recurrence relations – Orthogonality.

UNIT-II

Functions of a complex variable – Continuity – Differentiability – Analyticity – Properties – Cauchy-Riemann equations in Cartesian and polar coordinates. Harmonic and conjugate harmonic functions – Milne – Thompson method.

UNIT-III

Elementary functions: Exponential, trigonometric, hyperbolic functions and their properties – General power Z^C (c is complex), principal value.

UNIT-IV

Complex integration: Line integral – evaluation along a path and by indefinite integration – Cauchy's integral theorem – Cauchy's integral formula – Generalized integral formula.

UNIT-V

Complex power series: Radius of convergence – Expansion in Taylor's series, Maclaurin's series and Laurent series. Singular point –Isolated singular point – pole of order m – essential singularity.

UNIT-VI

Residue – Evaluation of residue by formula and by Laurent series - Residue theorem.
Evaluation of integrals of the type

(a) Improper real integrals $\int_{-\infty}^{\infty} f(x)dx$ (b) $\int_{c}^{c+2\pi} f(\cos\theta, \sin\theta)d\theta$

(c) $\int_{-\infty}^{\infty} e^{imx} f(x)dx$ (d) Integrals by identation.

UNIT-VII

Argument principle – Rouche's theorem – determination of number of zeros of complex polynomials - Maximum Modulus principle - Fundamental theorem of Algebra, Liouville's Theorem.

UNIT-VIII

Conformal mapping: Transformation by e^z, lnz, z^2, z^n (n positive integer), Sin z, cos z, z + a/z. Translation, rotation, inversion and bilinear transformation – fixed point – cross ratio – properties – invariance of circles and cross ratio – determination of bilinear transformation mapping 3 given points .

Text Books:

1. A text Book of Engineering Mathematics, Vol-III T. K. V. Iyengar, B. Krishna Gandhi and Others, S. Chand & Company.
2. A text Book of Engineering Mathematics, C. Sankaraiah, V. G. S. Book Links.
3. A text Book of Engineering Mathematics, Shahnaz Bathul, Prentice Hall of India.
4. A text Book of Engineering Mathematics, P. Nageshwara Rao, Y. Narasimhulu & N. Prabhakar Rao, Deepthi Publications.

References:

1. A text Book of Engineering Mathematics, B. V. Raman, Tata Mc Graw Hill.
2. Advanced Engineering Mathematics, Irvin Kreyszig, Wiley India Pvt. Ltd.
3. A text Book of Engineering Mathematics, Thamson Book Collection.

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ELECTRICAL TECHNOLOGY

UNIT I - DC MACHINES
Principle of operation of DC Machines- EMF equation – Types of generators – Magnetization and load characteristics of DC generators

UNIT II - D.C. MOTORS
DC Motors – Types of DC Motors – Characteristics of DC motors – 3-point starters for DC shunt motor – Losses and efficiency – Swinburne's test – Speed control of DC shunt motor – Flux and Armature voltage control methods.

UNIT III- TRANSFORMERS
Principle of operation of single phase transformer – types – Constructional features – Phasor diagram on No Load and Load – Equivalent circuit

UNIT IV - PERFORMANCE OF TRANSFORMERS
Losses and Efficiency of transformer and Regulation – OC and SC tests – Predetermination of efficiency and regulation (Simple Problems).

UNIT V - THREE PHASE INDUCTION MOTOR
Principle of operation of three-phase induction motors –Slip ring and Squirrel cage motors – Slip-Torque characteristics – Efficiency calculation – Starting methods.

UNIT VI - ALTERNATORS
Alternators – Constructional features – Principle of operation – Types - EMF Equation
– Distribution and Coil span factors – Predetermination of regulation by Synchronous Impedance Method – OC and SC tests.

UNIT VII - SINGLE PHASE INDUCTION MOTORS
Principle of operation - Shaded pole motors – Capacitor motors, AC servomotor, AC tachometers, Synchros, Stepper Motors – Characteristics.

UNIT VIII - ELECTRICAL INSTRUMENTS
Basic Principles of indicating instruments – Moving Coil and Moving iron Instruments (Ammeters and Voltmeters).

TEXT BOOKS

1. Introduction to Electrical Engineering – M.S Naidu and S. Kamakshaiah, TMH Publ.
2. Basic Electrical Engineering - T.K. Nagasarkar and M.S.Sukhija, Oxford University Press, 2005

REFERENCES
1. Principles of Electrical Engineering - V.K Mehta, S.Chand Publications.
2. Theory and Problems of basic electrical engineering - I.J. Nagarath amd D.P Kothari, PHI Publications
3. Essentials of Electrical and Computer Engineering - David V. Kerns, JR. J. David Irwin

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ELECTROMAGNETIC WAVES AND TRANSMISSION LINES

UNIT I

ELECTROSTATICS [1]

Coulomb's Law, Electric Field Intensity – Fields due to Different Charge Distributions,Electric Flux Density, Gauss Law and Applications, Electric Potential, Relations Between E and V, Maxwell's Two Equations for Electrostatic Fields, Energy Density, Related Problems. Convection and Conduction Currents, Dielectric Constant, Isotropic and Homogeneous Dielectrics, Continuity Equation, Relaxation Time, Poisson's and Laplace's Equations; Capacitance – Parallel Plate, Coaxial, Spherical Capacitors, Related Problems.

UNIT II

Magneto Statics [1] Biot-Savart Law, Ampere's Circuital Law and Applications, Magnetic Flux Density, Maxwell's Two Equations for Magnetostatic Fields, Magnetic Scalar and Vector Potentials, Forces due to Magnetic Fields, Ampere's Force Law, Inductances and Magnetic Energy. Related Problems.

UNIT III

Maxwell's Equations (Time Varying Fields) [2] Faraday's Law and Transformer emf, Inconsistency of Ampere's Law and Displacement Current Density, Maxwell's Equations in Different Final Forms and Word Statements. Conditions at a Boundary Surface : Dielectric-Dielectric and Dielectric-Conductor Interfaces. Related Problems [2,1].

UNIT IV

EM Wave Characteristics - I [2] Wave Equations for Conducting and Perfect Dielectric Media, Uniform Plane Waves – Definition, All Relations Between E & H. Sinusoidal Variations. Wave Propagtion in Lossless and Conducting Media. Conductors & Dielectrics – Characterization, Wave Propagation in Good Conductors and Good Dielectrics. Polarization. Related Problems.

UNIT V

EM Wave Characteristics – II [2] Reflection and Refraction of Plane Waves – Normal and Oblique Incidences, for both Perfect Conductor and Perfect Dielectrics, Brewster Angle, Critical Angle and Total Internal Reflection, Surface Impedance. Poynting Vector and Poynting Theorem – Applications, Power Loss in a Plane Conductor. Related Problems [2,1].

UNIT V

Guided Waves Parallel Plane Waveguides [2] : Introduction, TE, TM, TEM Modes - Concepts and Analysis, Cut-off Frequencies, Velocities, Wavelengths, Wave Impedances. Attenuations Factor – Expression for TEM Case. Related Problems.

UNIT VII

Transmission Lines – I Types, Parameters, Transmission Line Equations, Primary & Secondary Constants, Expressions for Characeristic Impedance, Propagation Constant, Phase and Group Velocities, Infinite Line Concepts, Losslessness/Low Loss Characterization, Distortion – Condition for Distortionlessness and Minimum Attenuation, Loading - Types of Loading. Related Problems.

UNIT VIII

Transmission Lines – II Input Impedance Relations, SC and OC Lines, Reflection Coefficient, VSWR. UHF Lines as Circuit Elements; /4, /2, /8 Lines – Impedance Transformations. Smith Chart – Configuration and Applications, Single and Double Stub Matching. Related Problems.

TEXT BOOKS:

1. Elements of Electromagnetics – Matthew N.O. Sadiku, Oxford Univ. Press, 3rd ed., 2001.
2. Electromagnetic Waves and Radiating Systems – E.C. Jordan and K.G. Balmain, PHI, 2nd Edition, 2000.

REFERENCES :

1. Engineering Electromagnetics – Nathan Ida, Springer (India) Pvt. Ltd., New Delhi, 2nd ed., 2005.
2. Networks, Lines and Fields – John D. Ryder, PHI, 2nd ed.,1999. Engineering Electromagnetics – William H. Hayt Jr. and John A. Buck, TMH, 7th ed., 2006.
3. Electromagnetic Field Theory and Transmission Lines – G.S.N. Raju, Pearson Edn. Pte. Ltd., 2005.
4. Transmission Lines and Networks – Umesh Sinha, Satya Prakashan (Tech.India Publications), New Delhi, 2001.

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SIGNALS AND SYSTEMS

UNIT I

SIGNAL ANALYSIS

Analogy between vectors and signals, Orthogonal signal space, Signal approximation using orthogonal functions, Mean square error, Closed or complete set of orthogonal functions, Orthogonality in complex functions, Exponential and sinusoidal signals, Concepts of Impulse function, Unit step function, Signum function.

UNIT II

FOURIER SERIES REPRESENTATION OF PERIODIC SIGNALS

Representation of Fourier series, Continuous time periodic signals, properties of Fourier series, Dirichlet's conditions, Trigonometric Fourier series and Exponential Fourier series, Complex Fourier spectrum

UNIT III

FOURIER TRANSFORMS

Deriving Fourier transform from Fourier series, Fourier transform of arbitrary signal, Fourier transform of standard signals, Fourier transform of periodic signals, properties of Fourier transforms, Fourier transforms involving impulse function and Signum function. Introduction to Hilbert Transform.

UNIT IV

SIGNAL TRANSMISSION THROUGH LINEAR SYSTEMS

Linear system, impulse response, Response of a linear system, Linear time invariant (LTI) system, Linear time variant (LTV) system, Transfer function of a LTI system. Filter characteristics of linear systems. Distortion less transmission through a system, Signal bandwidth, system bandwidth, Ideal LPF, HPF and BPF characteristics, Causality and Poly-Wiener criterion for physical realization, relationship between bandwidth and rise time.

UNIT V

CONVOLUTION AND CORRELATION OF SIGNALS

Concept of convolution in time domain and frequency domain, Graphical representation of convolution, Convolution property of Fourier transforms. Cross correlation and auto correlation of functions, properties of correlation function, Energy density spectrum, Parseval's theorem, Power density spectrum, Relation between auto correlation function and energy/power spectral density function.Relation between convolution and correlation, Detection of periodic signals in the presence of noise by correlation, Extraction of signal from noise by filtering.

UNIT VI

SAMPLING

Sampling theorem – Graphical and analytical proof for Band Limited Signals, impulse sampling, Natural and Flat top Sampling, Reconstruction of signal from its samples, effect of under sampling – Aliasing, Introduction to Band Pass sampling.

UNIT VII

LAPLACE TRANSFORMS

Review of Laplace transforms, Partial fraction expansion, Inverse Laplace transform, Concept of region of convergence (ROC) for Laplace transforms, constraints on ROC for various classes of signals, Properties of L.T's relation between L.T's, and F.T. of a signal. Laplace transform of certain signals using waveform synthesis.

UNIT VIII

Z–TRANSFORMS

Fundamental difference between continuous and discrete time signals, discrete time signal representation using complex exponential and sinusoidal components, Periodicity of discrete time usingcomplex exponential signal, Concept of Z- Transform of a discrete sequence. Distinction between Laplace, Fourier and Z transforms. Region of convergence in Z-Transform, constraints on ROC for various classes of signals, Inverse Z-transform, properties of Z-transforms.

TEXT BOOKS:

1. Signals, Systems & Communications - B.P. Lathi, BS Publications, 2003.
2. Signals and Systems - A.V. Oppenheim, A.S. Willsky and S.H. Nawab, PHI, 2nd Edn.

REFERENCES

1. Signals & Systems - Simon Haykin and Van Veen,Wiley, 2nd Edition.
2. Network Analysis - M.E. Van Valkenburg, PHI Publications, 3rd Edn., 2000.
3. Signals & Systems Analysis Using Transformation Methods & MAT Lab - Robert:, TMH, 2003.
4. Signals, Systems and Transforms - C. L. Philips, J.M.Parr and Eve A.Riskin, Pearson education., 3rd Edition, 2004.

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PULSE AND DIGITAL CIRCUITS

UNIT I

LINEAR WAVESHAPING

High pass, low pass RC circuits, their response for sinusoidal, step, pulse, square and ramp inputs. RC network as differentiator and integrator, attenuators, its applications in CRO probe, RL and RLC circuits and their response for step input, Ringing circuit.

UNIT II

NON-LINEAR WAVE SHAPING

Diode clippers, Transistor clippers, clipping at two independent levels, Transfer characteristics of clippers, Emitter coupled clipper, Comparators, applications of voltage comparators, clamping operation, clamping circuits using diode with different inputs, Clamping circuit theorem, practical clamping circuits, effect of diode characteristics on clamping voltage, Transfer characteristics of clampers.

UNIT III

SWITCHING CHARACTERISTICS OF DEVICES

Diode as a switch, piecewise linear diode characteristics, Transistor as a switch, Break down voltage consideration of transistor, saturation parameters of Transistor and their variation with temperature, Design of transistor switch, transistor-switching times.

UNIT IV

MULTIVIBRATORS

Analysis and Design of Bistable, Monostable, Astable Multivibrators and Schmitt trigger using transistors.

UNIT V

TIME BASE GENERATORS

General features of a time base signal, methods of generating time base waveform, Miller and Bootstrap time base generators – basic principles, Transistor miller time base generator, Transistor Bootstrap time base generator, Current time base generators.

UNIT VI

SYNCHRONIZATION AND FREQUENCY DIVISION

Principles of Synchronization, Frequency division in sweep circuit, Astable relaxation circuits, Monostable relaxation circuits, Synchronization of a sweep circuit with
symmetrical signals, Sine wave frequency division with a sweep circuit.

UNIT VII

SAMPLING GATES

Basic operating principles of sampling gates, Unidirectional and Bi-directional
sampling gates, Reduction of pedestal in gate circuits, Applications of sampling
gates.

UNIT VIII

REALIZATION OF LOGIC GATES USING DIODES & TRANSISTORS

AND, OR gates using Diodes, Resistor, Transistor Logic, Diode Transistor Logic.

TEXT BOOKS:

1. Pulse, Digital and Switching Waveforms - J. Millman and H. Taub, McGraw-Hill, 1991.
2. Solid State Pulse circuits - David A. Bell, PHI, 4th Edn.., 2002 .

REFERENCES

1. Pulse and Digital Circuits – A. Anand Kumar, PHI.
2. Wave Generation and Shaping - L. Strauss.
3. Pulse, Digital Circuits and Computer Fundamentals - R.Venkataraman.

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SWITCHING THEORY AND LOGIC DESIGN

UNIT I

NUMBER SYSTEMS & CODES : Philosophy of number systems – complement representation of negative numbers-binary arithmetic-binary codes-error detecting & error correcting codes –hamming codes.

UNIT II

BOOLEAN ALGEBRA AND SWITCHING FUNCTIONS : Fundamental postulates of Boolean Algebra - Basic theorems and properties - switching functions–Canonical and Standard forms-Algebraic simplification digital logic gates, properties of XOR gates –universal gates-Multilevel NAND/NOR realizations.

UNIT III

MINIMIZATION OF SWITCHING FUNCTIONS : Map method, Prime implicants, Don't care combinations, Minimal SOP and POS forms, Tabular Method, Prime –Implicant chart, simplification rules.

UNIT IV

COMBINATIONAL LOGIC DESIGN

Design using conventional logic gates, Encoder, Decoder, Multiplexer, De-Multiplexer, Modular design using IC chips, MUX Realization of switching functions Parity bit generator, Code-converters, Hazards and hazard free realizations.

UNIT V

PROGRAMMABLE LOGIC DEVICES, THRESHOLD LOGIC : Basic PLD's-ROM, PROM, PLA, PLD Realization of Switching functions using PLD's. Capabilities and limitations of Threshold gate, Synthesis of Threshold functions, Multigate Synthesis.

UNIT VI

SEQUENTIAL CIRCUITS - I : Classification of sequential circuits (Synchronous, Asynchronous, Pulse mode, Level mode with examples) Basic flip-flops-Triggering and excitation tables. Steps in synchronous sequential circuit design. Design of modulo-N Ring & Shift counters, Serial binary adder,sequence detector.

UNIT VII

SEQUENTIAL CIRCUITS - II : Finite state machine-capabilities and limitations, Mealy and Moore models-minimization of completely specified and incompletely specified sequential machines, Partition techniques and Merger chart methods-concept of minimal cover table.

UNIT VIII

ALGOROTHIMIC STATE MACHINES : Salient features of the ASM chart-Simple examples-System design using data path and control subsystems-control implementations-examples of Weighing machine and Binary multiplier.

TEXTBOOKS :

1. Switching & Finite Automata theory – Zvi Kohavi, TMH,2nd Edition.
2. Digital Design – Morris Mano, PHI, 3rd Edition, 2006.

REFERENCES :

1. An Engineering Approach To Digital Design – Fletcher, PHI. Digital Logic – Application and Design – John M. Yarbrough, Thomson.
2. Fundamentals of Logic Design – Charles H. Roth, Thomson Publications, 5th Edition, 2004.
3. Digital Logic Applications and Design – John M. Yarbrough, Thomson Publications, 2006.

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ELECTRICAL TECHNOLOGY LAB

PART – A

1. Serial and Parallel Resonance – Timing, Resonant frequency, Bandwidth and Q-factor determination for RLC network.
2. Time response of first order RC/RL network for periodic non-sinusoidal inputs – time constant and steady state error determination.
3. Two port network parameters – Z-Y Parameters, chain matrix and analytical verification.
4. Verification of Superposition and Reciprocity theorems.
5. Verification of maximum power transfer theorem. Verification on DC, verification on AC with Resistive and Reactive loads.
6. Experimental determination of Thevenin's and Norton's equivalent circuits and verification by direct test.

PART – B

1. Magnetization characteristics of D.C. Shunt generator. Determination of critical field resistance.
2. Swinburne's Test on DC shunt machine (Predetermination of efficiency of a given DC Shunt machine working as motor and generator).
3. Brake test on DC shunt motor. Determination of performance characteristics.
4. OC & SC tests on Single-phase transformer (Predetermination of efficiency and regulation at given power factors and determination of equivalent circuit).
5. Brake test on 3-phase Induction motor (performance characteristics).
6. Regulation of alternator by synchronous impedance method.

Note: Any **TEN** of the above experiments are to be conducted

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PULSE AND DIGITAL CIRCUITS LAB

Minimum Twelve experiments to be conducted:

1. Linear wave shaping.
2. Non Linear wave shaping – Clippers.
3. Non Linear wave shaping – Clampers.
4. Transistor as a switch.
5. Study of Logic Gates & Some applications.
6. Study of Flip-Flops & some applications.
7. Sampling Gates.
8. Astable Multivibrator.
9. Monostable Multivibrator.
10. Bistable Multivibrator.
11. Schmitt Trigger.
12. UJT Relaxation Oscillator.
13. Bootstrap sweep circuit.

Equipment required for Laboratories:

1. RPS - 0 – 30 V
2. CRO - 0 – 20 M Hz.
3. Function Generators - 0 – 1 M Hz
4. Components
5. Multi Meters